# Errata zu
# **Technische Mechanik / Technical Mechanics**

v1.1

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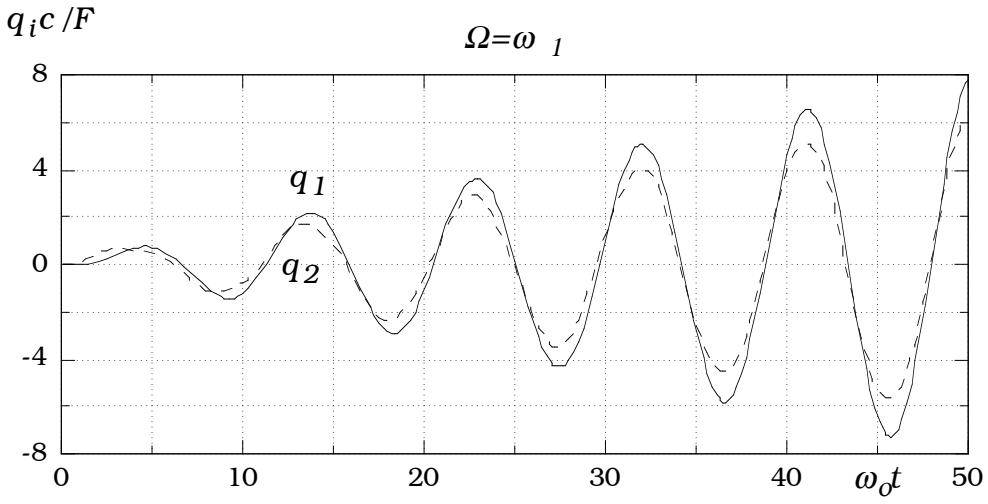
1. Auflage, Teubner Verlag

| **Kap.** | **Seite** | **Beschreibung** |
|---|---|---|
| 2 | 6 | $F = \left\| \vec{F} \right\| = \sqrt{F_x{}^2 + F_y{}^2 + F_z{}^2}.$ |
| 2 | 6 | 3. Absatz links Zeilenabstand |
| 2 | 11 | $\sum_{i=1}^{n} \vec{F}_i^{(1)} = \sum_{j=1}^{m} \vec{F}_j^{(2)}$ |
| 3 | 21 | Bsp. Einzug |
| 3 | 21 | $\begin{aligned} 2F_o + B_x &= 0, \\ -3F_o + B_y + C_y &= 0, \\ M_o - 2F_o 2l + 3F_o l + C_y 3l &= 0; \end{aligned} \quad \Rightarrow \quad \begin{aligned} B_x &= -2F_o, \\ B_y &= \frac{8}{3}F_o + \frac{M_o}{3l}, \\ C_y &= \frac{F_o}{3} - \frac{M_o}{3l}. \end{aligned}$ |
| 4 | 33 | $\overrightarrow{PQ_a} = \vec{a} ds_a \quad \rightarrow \quad \overrightarrow{P^* Q_a^*} = \vec{a}^* ds_a{}^*$ |
| 7 | 56 | $\boldsymbol{\varepsilon} = \underbrace{(\boldsymbol{\varepsilon} - \frac{1}{3} e 1)}_{\boldsymbol{\varepsilon}^{(D)}} + \underbrace{(\frac{1}{3} e 1)}_{\boldsymbol{\varepsilon}^{(K)}}, \qquad \boldsymbol{\sigma} = \underbrace{(\boldsymbol{\sigma} - \frac{1}{3} s 1)}_{\boldsymbol{\sigma}^{(D)}} + \underbrace{(\frac{1}{3} s 1)}_{\boldsymbol{\sigma}^{(K)}},$ |
| 9 | 77 | rechts unten Doppelpunkt |
| 10 | 82 | $dA = \vec{e}_x \cdot (d\vec{r}_\eta \times d\vec{r}_\zeta) = (\hat{y}_1 \hat{z}_2 - \hat{y}_2 \hat{z}_1) d\eta d\zeta := D d\eta d\zeta.$ |
| 11 | 85 | 1. Zeile rechts: system of forces |
| 11 | 92 | $f_k = \frac{\partial U}{\partial F_k} = \frac{1}{2} \sum_{i=1}^{3} \sum_{j=1}^{3} (A_{ij} \delta_{ik} F_j + A_{ij} F_i \delta_{jk}) = \sum_{i=1}^{3} A_{ki} F_i,$ |
| 17 | 120 | camera tripot |
| 17 | 128 | Bild: $\left\|\vec{v}_A\right\| = \left\|\vec{v}_D\right\| = \left\|\vec{v}_B\right\|$ |
| 18 | 137 | $\Theta_{S11} = \int_m (s_2{}^2 + s_3{}^2) dm = \frac{m}{V} \int_{-l_3/2}^{l_3/2} \int_{-l_2/2}^{l_2/2} \int_{-l_1/2}^{l_1/2} (s_2{}^2 + s_3{}^2) ds_1 ds_2 ds_3,$ |
| 18 | 138 | dreimal $\Theta_{Sii} = \ldots = \rho \iiint \ldots$ , nicht $= \frac{\rho}{m} \iiint \ldots$ |
| 19 | 151 | $\begin{aligned} m\ddot{x}_S &= F_x, \\ m\ddot{y}_S &= F_y, \\ m\ddot{z}_S &= F_z. \end{aligned}$ |
| 20 | 160 | $A_y = \frac{1}{4} mg \tan\varphi, \qquad K = \frac{mg}{4} (\frac{1}{\cos\varphi} + 9\cos\varphi - 6\cos\varphi_o) + ml\psi_o^2.$ |
| 24 | 206 | Aus der kinematischen Zwangsbedingung |
| 26 | 217 | im Bild: $t > \tau$ |
| 26 | 231 | 1. Formelzeile $-\frac{\tau}{2\eta_1}\sin(\omega_1 t) \quad \rightarrow \quad -\frac{\omega_o t}{2\eta_1}\cos(\omega_1 t)$<br>4. Formelzeile $-\frac{\tau}{2\eta_2}\sin(\omega_2 t) \quad \rightarrow \quad -\frac{\omega_o t}{2\eta_2}\cos(\omega_2 t)$ |

Kap. 26, S. 231: Erster Resonanzfall / First Case of Resonance




Kap. 26, S. 232: Zweiter Resonanzfall / Second Case of Resonance